

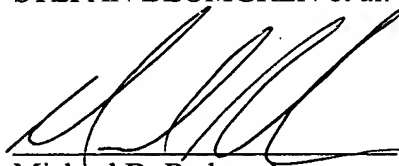
**REMARKS**

The foregoing amendment is being made to remove the multiple dependencies from claims 5 and 15 as filed. No new matter has been added. A favorable action on the merits of the pending claims is respectfully requested.

Respectfully submitted,

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By:



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DATE: **January 10, 2002**

Attachments: Amended claims with markings

2001-01-10 10:00:00

**VERSION WITH MARKINGS TO SHOW CHANGES MADE TO CLAIMS**

5. Method according to [any of the above claims] claim 1, characterized in that the transfer of the gripping mechanism is programmed in by means of a so called "teach-in" process, wherein a work cycle is programmed in by an operator by actual transfer of the gripping mechanism (12) through the work cycle, and successive registration of desired values is programmed in with respect to the rotor units forming part of the said motors (26,27), so that the control computer (51), through communication with a registration unit (52), can subsequently ensure automatic operation.

15. (Amended) Robot unit according to [any of the above mentioned claims] claim 1, characterized by a further drive belt (36), which is drivably connected to a transmission (39) on the lower end (22A) of the vertical beam (22), in order to be able to perform further motion with the gripping mechanism (12).